

Quadratic Sets

4.6 The Klein Quadratic Set

The Klein Quadratic Set

Def: A hyperbolic quadratic set of a 5-dimensional projective space is also called a *Klein quadratic set*.

We define a new geometry based on a Klein quadratic set.

Let C and C^* be the two equivalence classes of planes of a Klein quadratic set Q in a 5-dimensional projective space \mathbf{P} . We define the geometry \mathbf{S} as follows:

- a) the *points* of \mathbf{S} are the planes of C .
- b) the *lines* of \mathbf{S} are the points of Q .
- c) the *planes* of \mathbf{S} are the planes of C^* .
- d) the *incidence* between a line of \mathbf{S} and either a point or plane of \mathbf{S} is induced by the incidence in \mathbf{P} .
- e) a point π_1 of \mathbf{S} is *incident* with a plane π_2 of \mathbf{S} iff the planes π_1 and π_2 of \mathbf{P} are not disjoint (then by 4.5.5 they intersect each other in a line of \mathbf{P}).

Counts

Lemma 4.6.1: Let Q be a Klein quadratic set.

- a) Each Q -line is on exactly one plane of each equivalence class.
- b) If \mathbf{P} is finite of order q , then each point of Q is on exactly $q+1$ planes of each equivalence class.

Pf: a) Let g be an arbitrary Q -line. Consider a point P on g . We know that $Q_p \cap Q$ is a cone over a hyperbolic quadratic set Q'' .

The line g meets Q'' in some point. Through this point there pass two Q'' -lines, h and h' , one in each of the two classes of Q'' . It follows that the planes $\langle P, h \rangle$ and $\langle P, h' \rangle$ (which intersect in the line g) are the planes of the two equivalence classes through g .

b) By Theorem 4.5.4, each point of Q is on $(q+1)^2$ Q -lines. Each Q -plane through the point contains $q+1$ Q -lines. Since the planes in an equivalence class meet only at the point, there will be $q+1$ planes of each equivalence class through the point. □

3-space

Theorem 4.6.2: The geometry \mathbf{S} is a 3-dimensional projective space; more precisely, \mathbf{S} is isomorphic to a 3-dimensional subspace of \mathbf{P} .

Pf: We proceed in several steps.

Claim 1: Any two distinct points of \mathbf{S} are incident with exactly one line of \mathbf{S} .

This follows directly from 4.5.5 since any two planes of \mathbf{C} (two points of \mathbf{S}) intersect in precisely one point of \mathbf{Q} (a line of \mathbf{S}).

Claim 2: If two points π, π' of \mathbf{S} are incident with a plane π_2 of \mathbf{S} then any point of the line determined by them is also incident with π_2 (hence π_2 is a linear set). Moreover, the structure of the points and lines of \mathbf{S} incident with π_2 is a projective plane.

3-space

Theorem 4.6.2: The geometry \mathbf{S} is a 3-dimensional projective space; more precisely, \mathbf{S} is isomorphic to a 3-dimensional subspace of \mathbf{P} .

Pf(cont.):

Since π and π' are incident with π_2 in \mathbf{P} the planes π and π' intersect the plane π_2 in lines g and g' . The intersection of these lines is a point P which is the common point of π and π' . The point P is the line of \mathbf{S} through the points π and π' of \mathbf{S} . Since π_2 is in C' , any other plane from C through P intersects π_2 in a line, thus in \mathbf{S} the point that it represents is on the line represented by P and is incident with the plane π_2 of \mathbf{S} .

By Lemma 4.6.1 each line of π_2 is on exactly one plane of C . Thus the structure of points and lines of \mathbf{S} incident with π_2 is the structure of lines and points of \mathbf{P} on π_2 . This is the dual plane of π_2 and since π_2 is Desarguesian it is self-dual, thus isomorphic to π_2 .

3-space

Theorem 4.6.2: The geometry \mathbf{S} is a 3-dimensional projective space; more precisely, \mathbf{S} is isomorphic to a 3-dimensional subspace of \mathbf{P} .

Pf(cont.): **Claim 3:** Any three points of \mathbf{S} that are not on a common line of \mathbf{S} are incident with precisely one plane of \mathbf{S} .

Let π_1, π_2 and π_3 be three points of \mathbf{S} that are not incident with a common line of \mathbf{S} . These are three planes from C not through a common point of Q . Thus, the points $P_1 = \pi_2 \cap \pi_3$, $P_2 = \pi_1 \cap \pi_3$ and $P_3 = \pi_1 \cap \pi_2$ are distinct points of Q .

We now show that the plane π from C' through P_1 and P_2 also contains P_3 . Now π intersects π_1 and π_2 in lines g_1 and g_2 since π is in the other equivalence class and has a nonempty intersection with each plane. These two lines intersect in π at a point $X = g_1 \cap g_2 = (\pi \cap \pi_1) \cap (\pi \cap \pi_2) \subseteq \pi_1 \cap \pi_2 = P_3$.

Thus, the plane π of \mathbf{S} is incident with the points π_1, π_2 and π_3 of \mathbf{S} . Any other plane of \mathbf{S} through these points would have a line in common with π_2 and a line in common with π_3 , thus it would pass through P_1 . Similarly, it would pass through P_2 and P_3 and so would equal π .

3-space

Theorem 4.6.2: The geometry \mathbf{S} is a 3-dimensional projective space; more precisely, \mathbf{S} is isomorphic to a 3-dimensional subspace of \mathbf{P} .

Pf(cont.): These three claims imply that \mathbf{S} is a projective space.

Claim 4: The projective space \mathbf{S} has dimension 3.

For this we show that each line of \mathbf{S} and each plane of \mathbf{S} are incident with a common point of \mathbf{S} . It then follows that each plane of \mathbf{S} is a hyperplane, so \mathbf{S} has dimension 3.

Therefore, let P be a line of \mathbf{S} and π_2 a plane of \mathbf{S} which are not incident. So P is a point of Q and π_2 a plane in C' such that P is outside of π_2 . The tangent hyperplane Q_P intersects π_2 in a line g . Then $\pi_1 = \langle P, g \rangle$ is a Q -plane, which is in C since π_1 and π_2 have a line in common. Hence, π_1 is a point of \mathbf{S} that is incident with the line P and the plane π_2 of \mathbf{S} . □