

Solutions to Test on Ch. 9 & 10 – MATH 2421
Spring 2004

- (#1) In cylindrical coordinates, the *surface* $r = \cos(\theta)$, for $-\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2}$, assumes that z can be anything. How should we name this surface?

We recall that $r = \cos(\theta)$ is a *circle* of radius $R = \frac{1}{2}$ centered at $\left(\frac{1}{2}, 0\right)$ in the xy -plane. If we duplicate this circle in the z -axis direction, we have a right circular cylinder.

The correct answer is **(c)**.

- (#2) With which angle θ do we associate the plane $y = -x$?

The slope of this line in the xy -plane is $m = -1 = \tan(\theta)$.

The correct answer is **(d)** $\theta = \frac{3\pi}{4}$

- (#3) If $\mathbf{u} = \langle -2, 0, -4 \rangle$ and $\mathbf{v} = \langle 1, -1, 1 \rangle$, then which vector is equal to $\mathbf{Proj}_{\mathbf{v}}\mathbf{u}$?

$$\mathbf{Proj}_{\mathbf{v}}\mathbf{u} = \left(\frac{\mathbf{u} \cdot \mathbf{v}}{\mathbf{v} \cdot \mathbf{v}} \right) \mathbf{v} = \left(\frac{\langle -2, 0, -4 \rangle \cdot \langle 1, -1, 1 \rangle}{\langle 1, -1, 1 \rangle \cdot \langle 1, -1, 1 \rangle} \right) \langle 1, -1, 1 \rangle = \left(\frac{-2 + 0 - 4}{1 + 1 + 1} \right) \langle 1, -1, 1 \rangle = \left(\frac{-6}{3} \right) \langle 1, -1, 1 \rangle = \langle -2, 2, -2 \rangle. \quad \text{The correct answer is (c).}$$

- (#4) A cable runs from $P(1, 0)$ to $Q(6, 12)$. The tension vector has the same direction as \overrightarrow{PQ} , but has magnitude 100 pounds. Which vector below represents the tension vector?

$\overrightarrow{PQ} = \langle 5, 12 \rangle$. The unit vector associated with this vector is

$$\frac{1}{|\langle 5, 12 \rangle|} \langle 5, 12 \rangle = \frac{1}{13} \langle 5, 12 \rangle = \left\langle \frac{5}{13}, \frac{12}{13} \right\rangle.$$

Now multiply by this 100. The resulting vector will have the correct length and direction!

The correct answer is **(a)** $\frac{100}{13} \langle 5, 12 \rangle$.

- (#5) $x^2 + y^2 + z^2 + 2x - 2y = 25$. What is the radius of this sphere? Complete the square.

$$(x^2 + 2x + 1^2) + (y^2 - 2y + (-1)^2) + z^2 = 25 + 1^2 + (-1)^2$$

$$(x + 1)^2 + (y - 1)^2 + (z - 0)^2 = 27.$$

$$R = \sqrt{27} = 3\sqrt{3}. \quad [\text{The center is located at } C(-1, 1, 0).]$$

The correct answer is **(d)**.

- (#6) These are right circular cones and the central axis is the y -axis. It must be $y^2 = x^2 + z^2$.

The correct answer is **(e)**.

(#7) Suppose we want to move an object from $P(1, -3, 0)$ to $Q(15, 5, -6)$.

(a) $\vec{PQ} = \langle 14, 8, -6 \rangle$

(b) Write down the parametric equations which define the line in 3-D which passes through P and Q .

$$x = 14t + 1$$

$$y = 8t - 3$$

$$z = -6t + 0$$

(c) Suppose that the force $\mathbf{F} = \langle 2, 1, -3 \rangle$ moves the object from P to Q . Find the number of work units accomplished by the force.

$$\text{Work} = \mathbf{F} \cdot \vec{PQ} = \langle 2, 1, -3 \rangle \cdot \langle 14, 8, -6 \rangle = 28 + 8 + 18 = 54 \text{ work units.}$$

(#8) We have two planes: $x + 2y + 3z = 6$ and $-3x + 2y + 6z = 12$.

Find the acute ($0 \leq \alpha < \frac{\pi}{2}$) angle between the planes, also called the dihedral angle.

The answer is *not* one of the standard angles. We use the dot product between the two normal vectors.

$$\mathbf{n}_1 = \langle 1, 2, 3 \rangle \quad \mathbf{n}_2 = \langle -3, 2, 6 \rangle$$

$$\cos(\alpha) = \frac{\langle 1, 2, 3 \rangle \cdot \langle -3, 2, 6 \rangle}{|\langle 1, 2, 3 \rangle| * |\langle -3, 2, 6 \rangle|} = \frac{-3 + 4 + 18}{\sqrt{1^2 + 2^2 + 3^2} \sqrt{(-3)^2 + 2^2 + 6^2}} = \frac{19}{7\sqrt{14}}.$$

$$\alpha = \cos^{-1}\left(\frac{19}{7\sqrt{14}}\right) \doteq 43.5^\circ.$$

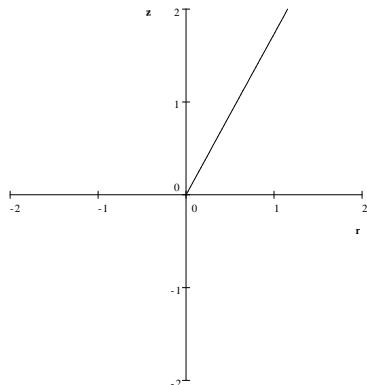
(#9) The upper cone $z = \sqrt{3}\sqrt{x^2 + y^2}$ can easily be transformed into cylindrical and spherical coordinates.

(a) Make one substitution and find the equation in cylindrical coordinates.

$$z = \sqrt{3} * r.$$

(b) Based on your previous work, show me what the trace (slice) looks like if I choose any of the θ -planes (rz-planes) through the z-axis.

In the rz-plane, this must be a straight line.



(c) Tougher. By making a few more substitutions and then some cancelling, show that the equation in spherical coordinates is $\phi = a \text{ constant angle}$.

$$z = \sqrt{3} * r \Rightarrow \rho \cos(\phi) = \sqrt{3} \rho \sin(\phi). \quad \text{Divide both sides by } \rho.$$

$$\cos(\phi) = \sqrt{3} \sin(\phi) \Rightarrow \frac{1}{\sqrt{3}} = \frac{\sin(\phi)}{\cos(\phi)} \Rightarrow \tan(\phi) = \frac{\sqrt{3}}{3} \Rightarrow \phi = \frac{\pi}{6}.$$

(#10) Find the standard form for the plane which contains the points $P(0, 0, 0)$, $Q(1, 2, -3)$, and $R(-2, 5, -4)$.

$$\overrightarrow{PQ} = \langle 1, 2, -3 \rangle \quad \overrightarrow{PR} = \langle -2, 5, -4 \rangle.$$

The normal vector for plane will be $\overrightarrow{PQ} \times \overrightarrow{PR} = \langle 1, 2, -3 \rangle \times \langle -2, 5, -4 \rangle = \langle 7, 10, 9 \rangle$.

The standard form for the plane is $7(x - 0) + 10(y - 0) + 9(z - 0) = 0$ or $7x + 10y + 9z = 0$.

(#11) We have $|\mathbf{r}| = 20$ feet and $|\mathbf{F}| = 16$ pounds. The measure of Angle A does not matter.

If we translate the force vector back to the tail of the lever arm vector, we essentially form a parallelogram.

- (a) Since Angle C measures 58° , the angle of separation must be $180^\circ - 58^\circ = 122^\circ$.
- (b) The shortest angular path from the level arm to the force vector is *clockwise*, so by the Right-hand Rule, the torque vector must point INTO the paper.
- (c) $|\mathbf{T}| = (20 \text{ feet})(16 \text{ lb}) \sin(122^\circ) = 310 * \sin(122^\circ) \text{ ft-lb}$.

(#12) True or False? No work is necessary.

- (a) If c is a nonzero scalar, then $|c\mathbf{v}|$ always equals $c|\mathbf{v}|$.
FALSE. If $c < 0$, then $|c\mathbf{v}| = |c| * |\mathbf{v}|$.
- (b) If \mathbf{u} and \mathbf{v} are nonzero vectors and $\mathbf{u} \cdot \mathbf{v} = 0$, then \mathbf{u} and \mathbf{v} must be parallel.
FALSE. We recall that \mathbf{u} and \mathbf{v} must be perpendicular (orthogonal).
- (c) If we have the coordinates $(\rho, \theta, \phi) = \left(2, \frac{\pi}{3}, \frac{\pi}{2}\right)$, then $z = 0$.
TRUE. In spherical coordinates, if $\phi = \frac{\pi}{2}$, then the point must lie in the xy-plane.

(#13) Match the equations with the appropriate shapes below.

- (i) $\rho = 7$
This is the sphere. The correct answer is **(a)**.
- (ii) $z = -r^2 = -(x^2 + y^2)$
This is the elliptic (circular) paraboloid which is bowl-shape downward.
- (iii) $x^2 - y^2 + z^2 = 4 \Rightarrow \frac{x^2}{4} - \frac{y^2}{4} + \frac{z^2}{4} = 1$
This is the hyperboloid of one sheet because the standard form has ONE negative sign.

(#14) Suppose we have the position function $\mathbf{r}(t) = \langle t, 4 - t^2 \rangle$ for $-2 \leq t \leq 2$.

- (a) Sketch the 2-D parabola which is associated with this position function.
This is the parabola, $y = 4 - x^2$, $-2 \leq t \leq 2$.
- (b) Sketch in the position vector $\mathbf{r}(1)$ with its tail at the origin.
 $\mathbf{r}(1) = \langle 1, 4 - 1^2 \rangle = \langle 1, 3 \rangle$.
- (c) $\mathbf{v}(t) = \langle 1, -2t \rangle \Rightarrow \mathbf{v}(1) = \langle 1, -2 \rangle$.

- (d) Sketch in $\mathbf{v}(1)$ so that we can see the geometric relationship between the velocity vector and the path of the object.

The initial point is $(1, 3)$ and the terminal point is $(2, 1)$. The vector is tangent to the curve and it shows that the object is moving from left to right (and also downward).

