

MATH 2421 (Test on Ch. 9 & 10)
Spring 2004 – half.tex

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Instructions. Show all work on free response questions. The numbers used in the calculations are relatively small. No decimal approximations to square roots are necessary. Circle the *best* answer for multiple-choice questions (no need to show work).

The multiple choice questions are worth 5 pts. each.

(#1) In cylindrical coordinates, the *surface* $r = \cos(\theta)$, for $-\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2}$, assumes that z can be anything. How should we name this surface?

- (a) ellipsoid
- (b) sphere
- (c) right circular cylinder
- (d) right cardioid cylinder
- (e) plane.

(#2) With which angle θ do we associate the plane $y = -x$?

- (a) $\theta = 0$
- (b) $\theta = \frac{\pi}{4}$
- (c) $\theta = \frac{\pi}{2}$
- (d) $\theta = \frac{3\pi}{4}$
- (e) $\theta = \pi$

(#3) If $\mathbf{u} = \langle -2, 0, -4 \rangle$ and $\mathbf{v} = \langle 1, -1, 1 \rangle$, then which vector is equal to $\mathbf{Proj}_{\mathbf{v}}\mathbf{u}$?

- (a) $\langle 1, -1, 1 \rangle$
- (b) $\langle -2, 2, -2 \rangle$
- (c) $\langle 2, -2, 2 \rangle$
- (d) $\langle -6, 6, -6 \rangle$
- (e) $\langle 6, -6, 6 \rangle$

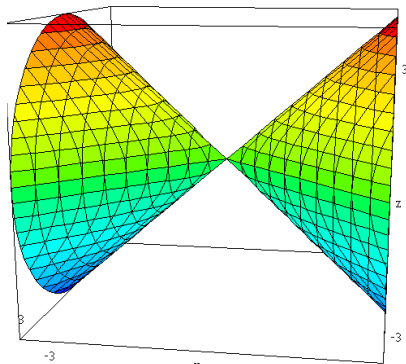
(#4) A cable runs from $P(1, 0)$ to $Q(6, 12)$. The tension vector has the same direction as \overrightarrow{PQ} , but has magnitude 100 pounds. Which vector below represents the tension vector?

- (a) $\frac{100}{13} \langle 5, 12 \rangle$
- (b) $\frac{100}{\sqrt{13}} \langle 5, 12 \rangle$
- (c) $\frac{13}{100} \langle 5, 12 \rangle$
- (d) $\langle \frac{500}{169}, \frac{1200}{169} \rangle$
- (e) $100 \left\langle \frac{6}{\sqrt{180}}, \frac{12}{\sqrt{180}} \right\rangle$

(#5) $x^2 + y^2 + z^2 + 2x - 2y = 25$. What is the radius of this sphere?

- (a) 5
- (b) 25
- (c) $\sqrt{23}$
- (d) $3\sqrt{3}$
- (e) 27

(#6) Orientation. Which equation best fits the figure?



- (a) $z^2 = x^2 + y^2$
- (b) $z^2 = x^2 - y^2$
- (c) $x^2 = y^2 + z^2$
- (d) $y = x^2 + z^2$
- (e) $y^2 = x^2 + z^2$

(#7) Suppose we want to move an object from $P(1, -3, 0)$ to $Q(15, 5, -6)$.

- (a) [2 pts.] Find \overrightarrow{PQ} .
- (b) [4 pts.] Write down the parametric equations which define the line in 3-D which passes through P and Q .
 $x =$
 $y =$
 $z =$
- (c) [4 pts.] Suppose that the force $\mathbf{F} = \langle 2, 1, -3 \rangle$ moves the object from P to Q . Find the number of work units accomplished by the force.

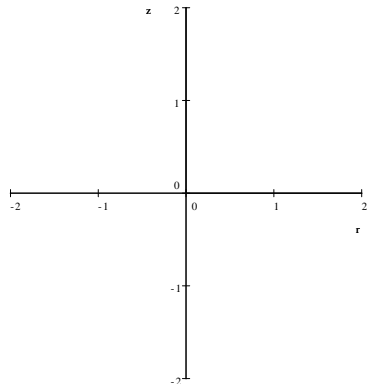
(#8) [9 pts.] We have two planes: $x + 2y + 3z = 6$ and $-3x + 2y + 6z = 12$.

Find the acute ($0 \leq \alpha < \frac{\pi}{2}$) angle between the planes, also called the dihedral angle.

The answer is *not* one of the standard angles. Just leave your answer in the form of an inverse trig. function...

(#9) The upper cone $z = \sqrt{3}\sqrt{x^2 + y^2}$ can easily be transformed into cylindrical and spherical coordinates.

- (a) [2 pts.] Make one substitution and find the equation in cylindrical coordinates.
- (b) [3 pts.] Based on your previous work, show me what the trace (slice) looks like if I choose any of the θ -planes (rz-planes) through the z-axis.

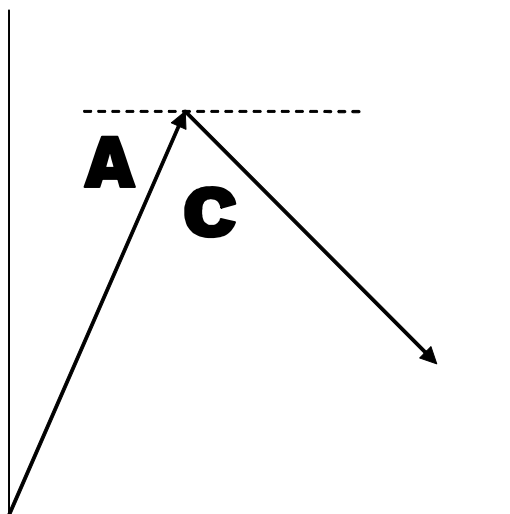


- (c) [4 pts.] Tougher. By making a few more substitutions and then some cancelling, show that the equation in spherical coordinates is $\phi = a \text{ constant angle}$.

(#10) [9 pts.] Find the standard form for the plane which contains the points $P(0, 0, 0)$, $Q(1, 2, -3)$, and $R(-2, 5, -4)$.

(#11) Here is a picture of the lever arm vector and a force. The level arm vector has its tail positioned at the origin. The force is applied to the head of the level arm vector. We have $|\mathbf{r}| = 20$ feet and $|\mathbf{F}| = 16$ pounds.

Angle A measures 61° and Angle C measures 58° .



- (a) [3 pts.] Find the angle of separation α , in degrees.
- (b) [3 pts.] In which direction will the torque vector \mathbf{T} point?
- (c) [3 pts.] Calculate $|\mathbf{T}|$.

(#12) [2 pts. each] True or False? No work is necessary.

- (a) ___ If c is a nonzero scalar, then $|c\mathbf{v}|$ always equals $c|\mathbf{v}|$.
- (b) ___ If \mathbf{u} and \mathbf{v} are nonzero vectors and $\mathbf{u} \cdot \mathbf{v} = 0$, then \mathbf{u} and \mathbf{v} must be parallel.
- (c) ___ If we have the coordinates $(\rho, \theta, \phi) = (2, \frac{\pi}{3}, \frac{\pi}{2})$, then $z = 0$.

(#13) [3 pts. each] Match the equations with the appropriate shapes below.

- (i) ___ $\rho = 7$
- (ii) ___ $z = -r^2$
- (iii) ___ $x^2 - y^2 + z^2 = 4$

- (a) sphere
- (b) elliptic paraboloid
- (c) hyperbolic paraboloid
- (d) hyperbolic cylinder
- (e) hyperboloid of one sheet
- (f) hyperboloid of two sheets
- (g) plane

(#14) Suppose we have the position function $\mathbf{r}(t) = \langle t, 4 - t^2 \rangle$ for $-2 \leq t \leq 2$.

- (a) [2 pt.] Sketch the 2-D parabola which is associated with this position function.
- (b) [2 pts.] Sketch in the position vector $\mathbf{r}(1)$ with its tail at the origin.
- (c) [3 pts.] Calculate $\mathbf{v}(1)$.
- (d) [2 pts.] Sketch in $\mathbf{v}(1)$ so that we can see the geometric relationship between the velocity vector and the path of the object.

