

University of Colorado at Denver — Mathematics Department

Applied Linear Algebra Preliminary Exam

January 13, 2006

Name: \_\_\_\_\_

Exam Rules:

- This is a closed book exam. Once the exam begins, you have 4 hours to do your best. Submit as many solutions as you can. All solutions will be graded and your final grade will be based on your six best solutions.
- Each problem is worth 20 points; parts of problems have equal value unless otherwise specified.
- Justify your solutions: cite theorems that you use, provide counter-examples for disproof, give explanations, and show calculations for numerical problems.
- If you are asked to prove a theorem, do not merely quote that theorem as your proof; instead, produce an independent proof.
- Begin each solution on a new page and use additional paper, if necessary.
- Write legibly using a dark pencil or pen.
- Notation:  $\mathfrak{R}$  denotes the set of real numbers;  $\mathcal{C}$  denotes the set of complex numbers;  $\mathbb{Z}$  denotes the set of integers; and,  $\mathbb{Q}$  denotes the set of rational numbers. These extend to vector spaces as  $\mathfrak{R}^n$ ,  $\mathcal{C}^n$ ,  $\mathbb{Z}^n$ , and  $\mathbb{Q}^n$ , respectively.  $\mathcal{L}(V)$  denotes the set of linear operators on  $V$ . Other notation will be defined as needed.
- Ask the proctor if you have any questions.

Good luck!

- |          |          |
|----------|----------|
| 1. _____ | 5. _____ |
| 2. _____ | 6. _____ |
| 3. _____ | 7. _____ |
| 4. _____ | 8. _____ |

Total \_\_\_\_\_

DO NOT TURN THE PAGE UNTIL TOLD TO DO SO.

1. Let

$$A = \begin{bmatrix} -10 & 36 & 36 \\ -3 & 11 & 9 \\ 0 & 0 & 2 \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} 2 & 0 & 0 \\ 9 & 5 & -6 \\ 9 & 3 & -4 \end{bmatrix}.$$

Are  $A$  and  $B$  similar matrices? Why or why not?

**Solution:** The characteristic polynomial of  $A$  is  $(2-\lambda)((-10-\lambda)(11-\lambda)+108) = (2-\lambda)(-2-\lambda+\lambda^2) = (2-\lambda)^2(-1-\lambda)$ . Thus,  $A$  has eigenvalues  $-1, 2, 2$ . Solving  $(A-2I)x=0$  reveals that the eigenspace for  $\lambda=2$  has dimension 2. Thus,  $A$  has a complete set of linearly independent eigenvectors, so is diagonalizable. Thus,  $A$

is similar to the diagonal matrix  $D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ .

Similarly, the characteristic polynomial of  $B$  is  $(2-\lambda)((5-\lambda)(-4-\lambda)+18) = (2-\lambda)^2(-1-\lambda)$ . So  $B$  has the same eigenvalues as  $A$ , and the eigenspace of  $\lambda=2$  also has dimension 2. Thus,  $B$  is similar to  $D$ . Since  $A$  and  $B$  are similar to the same diagonal matrix  $D$ , they are similar.

2. Let  $V$  be a complex inner product space. For  $T \in \mathcal{L}(V)$ , define  $H = \frac{1}{2}(T+T^*)$  and  $S = \frac{1}{2}(T-T^*)$ . Prove that  $T$  is normal if every eigenvector of  $H$  is also an eigenvector of  $S$ .

**Solution:** The key theorem needed for this problem is that an operator  $T$  on a complex inner-product space  $V$  is normal if and only if  $V$  has an orthonormal basis consisting of eigenvectors of  $T$ .

$H$  is clearly self-adjoint (and therefore normal), so it has an orthonormal set  $\mathcal{B}$  of eigenvectors that form a basis for  $V$ . If every eigenvector of  $H$  is an eigenvector of  $S$ , then for each  $v \in \mathcal{B}$ ,

$$Tv = (H+S)v = (\lambda+\mu)v,$$

where  $\lambda$  and  $\mu$  are the eigenvalues associated with  $v$  for  $H$  and  $S$ , respectively. It follows that all the vectors in the orthonormal basis  $\mathcal{B}$  are eigenvectors of  $T$ , so by the theorem stated above,  $T$  is normal.

3. Let  $A$  be an  $m \times n$  real matrix and  $b \in \mathbb{R}^m$ . Show that exactly one of the following systems has a solution:

- i)  $Ax = b$
- ii)  $A^T y = 0, \quad y^T b \neq 0$ .

Note: Our notation is  $y = \begin{bmatrix} y_1 \\ \vdots \\ y_m \end{bmatrix}$ , so  $y^T = [y_1, \dots, y_m]$ .

**Solution:** If  $b \in \text{col } A$ , then statement i) has a solution, but since  $\text{col } A \perp \text{null } A^T$ , statement ii) has no solution.

If  $b \notin \text{col } A$ , then statement i) does not have a solution. In this case, let  $z = \text{proj}_{\text{col } A} b$  (the orthogonal projection of  $b$  onto the column space of  $A$ ), and define  $y = b - z$ . Note that  $y \neq 0$  (since  $b \notin \text{col } A$ ). Note also that since  $z$  is an orthogonal projection,  $y \in (\text{col } A)^\perp = \text{null } A^T$ . Thus,  $A^T y = 0$  and  $y^T b = y^T(y+z) = y^T y \neq 0$ , so statement ii) has a solution.

4. Consider the matrix  $A = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$ . Let  $b \in \mathbb{R}^2$  be a unit vector and let  $\delta b \in \mathbb{R}^2$  be a small perturbation vector, with  $\|\delta b\| = \epsilon > 0$ . Let  $x$  solve  $Ax = b$ , and let  $\delta x$  be the error associated with the perturbation  $\delta b$ , which satisfies  $A(x + \delta x) = b + \delta b$ .
- Calculate the condition number of  $A$ .
  - Determine the least upper bound on the relative error  $\frac{\|\delta x\|}{\|x\|}$ .
  - Find a  $b$  and  $\delta b$  for which this upper bound is achieved (subject to  $\|b\| = 1$  and  $\|\delta b\| = \epsilon$ ).

**Solution:**

- The eigenvalues of  $A$  are  $\lambda_1 = 3$  and  $\lambda_2 = 1$ . Since  $A$  is symmetric,  $\|A\| = \max\{|\lambda_1|, |\lambda_2|\} = 3$  and  $\|A^{-1}\| = \max\{|1/\lambda_1|, |1/\lambda_2|\} = 1$ . Thus,  $c(A) = \|A\| \|A^{-1}\| = 3$ .

(b)

$$\frac{\|\delta x\|}{\|x\|} \leq c(A) \frac{\|\delta b\|}{\|b\|} = 3\epsilon.$$

- Observe that  $\delta x = A^{-1}\delta b$ , and  $x = A^{-1}b$ . The relative error is maximized by choosing the unit vector  $b$  that minimizes  $\|x\|$  and by choosing the perturbation vector  $\delta b$  that maximizes  $\|\delta x\|$ , subject to  $\|\delta b\| = \epsilon$ . This is accomplished by choosing  $b$  to be an eigenvector associated with the smallest eigenvalue of  $A^{-1}$ ,  $1/\lambda_1$ , and choosing  $\delta b$  to be an eigenvector associated with the largest eigenvalue of  $A^{-1}$ ,  $1/\lambda_2$ . In particular,  $b = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ , and  $\delta b = \frac{\epsilon}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ . Then  $\|x\| = \left\| \frac{1}{\lambda_1} b \right\| = \frac{1}{3}$ , and  $\|\delta x\| = \left\| \frac{1}{\lambda_2} \delta b \right\| = \epsilon$ . Thus  $\|\delta x\| / \|x\| = 3\epsilon$ .

5. Let  $A$  and  $B$  be  $n \times n$  complex matrices with both having characteristic polynomial equal to  $f(x) = (x - c_1)^{d_1} \cdots (x - c_k)^{d_k}$ , where  $1 \leq d_i \leq 3$  for  $1 \leq i \leq k$ . Prove that  $A$  and  $B$  are similar if and only if they have the same minimal polynomial. Give two  $4 \times 4$  matrices  $A$  and  $B$  which are not similar but which have the same minimal and characteristic polynomials.

**Solution:** We know that  $A$  and  $B$  are similar if and only if they have the same Jordan form. Moreover, the Jordan form is the direct sum of the Jordan forms for each of the eigenvalues  $c_1, \dots, c_k$ . If  $J$  is the Jordan form for a complex matrix with precisely one eigenvalue  $c$ , where  $c$  has algebraic multiplicity  $d$  at most three, then  $J$  is completely determined as soon as its minimal polynomial is fixed. Then the characteristic poly of  $J$  is  $(x - c)^d$ ,  $1 \leq d \leq 3$ , and the minimal polynomial is  $(x - c)^r$ , where  $1 \leq r \leq d$ .

Case 1. The minimal polynomial of  $J$  is  $p(x) = (x - c)$ . In this case  $J$  is the direct sum of  $d$  copies of  $[c]$ , so there are three possibilities.

Case 2. The minimal polynomial of  $J$  is  $p(x) = (x - c)^2$ . In this case  $J$  is the direct sum of  $\begin{bmatrix} c & 1 \\ 0 & c \end{bmatrix}$  and zero or one copy of  $[c]$  depending on whether  $d = 2$  or  $d = 3$ , so there are two possibilities.

Case 3. The minimal polynomial of  $J$  is  $p(x) = (x - c)^3$ . In this case  $d$  is forced to equal 3 and

$$J = \begin{bmatrix} c & 1 & 0 \\ 0 & c & 1 \\ 0 & 0 & c \end{bmatrix}.$$

For the second part of the problem, let

$$A = \begin{bmatrix} c & 1 & 0 & 0 \\ 0 & c & 0 & 0 \\ 0 & 0 & c & 1 \\ 0 & 0 & 0 & c \end{bmatrix} \quad \text{and} \quad B = \begin{bmatrix} c & 1 & 0 & 0 \\ 0 & c & 0 & 0 \\ 0 & 0 & c & 0 \\ 0 & 0 & 0 & c \end{bmatrix}.$$

Both of these matrices are in Jordan form and have the same minimal polynomial  $(x - c)^2$ . But since the Jordan forms are different,  $A$  and  $B$  are not similar.

6. Let  $\mathcal{P}_2(\mathfrak{R})$  denote the usual vector space of all polynomials with coefficients from the reals and with degree at most 2. Define the real inner product  $\langle f, g \rangle = \int_0^1 f(x)g(x)dx$ . Find the unique polynomial  $q \in \mathcal{P}_2(\mathfrak{R})$  such that for all  $p \in \mathcal{P}_2(\mathfrak{R})$ ,  $\langle p, q \rangle = \int_0^1 p(x) \cos(\pi x) dx$ . (Hint: Applying the Gram-Schmidt process to the basis  $\{1, x, x^2\}$  yields the orthonormal basis

$$e_0 = 1; \quad e_1 = \sqrt{3}(-1 + 2x); \quad e_2 = \sqrt{5}(1 - 6x + 6x^2).)$$

**Solution:** Given an orthonormal basis  $\{e_0, e_1, e_2\}$  for  $\mathcal{P}_2(\mathfrak{R})$ , the desired vector  $q$  can be written in the form

$$q = \langle q, e_0 \rangle e_0 + \langle q, e_1 \rangle e_1 + \langle q, e_2 \rangle e_2 = \phi(e_0)e_0 + \phi(e_1)e_1 + \phi(e_2)e_2,$$

where  $\phi$  is the functional on  $\mathcal{P}_2(\mathfrak{R})$  defined by

$$\phi(p) = \int_0^1 p(x)(\cos(\pi x)) dx.$$

Using the orthonormal basis defined in the hint and evaluating, we have

$$\phi(e_0) = 0, \quad \phi(e_1) = \frac{-4\sqrt{3}}{\pi^2}, \quad \phi(e_2) = 0,$$

$$\text{so } q(x) = \frac{-4\sqrt{3}}{\pi^2}e_1 = \frac{12 - 24x}{\pi^2}.$$

7. (Vandermonde Determinant)

Let  $A$  be the  $n \times n$  matrix whose entries are

$$A = \begin{bmatrix} 1 & t_1 & t_1^2 & \cdots & t_1^{n-1} \\ 1 & t_2 & t_2^2 & \cdots & t_2^{n-1} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & t_n & t_n^2 & \cdots & t_n^{n-1} \end{bmatrix},$$

where  $t_1, \dots, t_n$  are complex variables.

Prove that

$$\det A = \prod_{1 \leq j < i \leq n} (t_i - t_j).$$

(Hint: perform an elementary row operation on  $A$  to show that  $(t_i - t_j)$  divides  $\det A$ .)

**Solution:** Subtracting row  $j$  from row  $i$  does not change the determinant and makes it clear that  $(t_i - t_j)$  divides the determinant. Hence  $\prod_{1 \leq j < i \leq n} (t_i - t_j)$  divides  $\det A$ . Clearly the determinant is a polynomial in the  $t_i$ 's having degree  $0 + 1 + 2 + \cdots + n - 1 = (n - 1)n/2$ . This is also the degree of the product, so to show equality we need only check the coefficient on a specific term, say the term  $1 \cdot t_2 \cdot t_3^2 \cdots t_n^{n-1}$ . Using a standard definition of the determinant,

$$\det A = \sum_{\sigma} (\text{sgn } \sigma) A_{1(\sigma_1)} A_{2(\sigma_2)} \cdots A_{n(\sigma_n)}, \quad (1)$$

the sum being extended over the distinct permutations  $\sigma$  of degree  $n$ , we see that the coefficient on this term in  $\det A$  is  $+1$ . We see that the only way to get this term in the product  $\prod_{1 \leq j < i \leq n} (t_i - t_j)$  is to choose  $t_n$  from all factors that have it, then choose  $t_{n-1}$  from all the remaining factors that have it, etc. The coefficient here is then clearly 1.

8. Let  $A$  be an  $m \times n$  matrix and  $B$  be an  $n \times p$  matrix. Prove that  $\dim \text{null}(AB) \leq \dim \text{null}(A) + \dim \text{null}(B)$ . (Hint: In this exercise it is convenient to let  $V = \{x \in \mathcal{R}^p : ABx = 0\}$  and  $W = \{y = Bx \in \mathcal{R}^n : Ay = 0\}$ . Then consider the map  $T_B : V \rightarrow W$  defined by  $T_B : x \mapsto Bx$  for all  $x \in V$ .)

**Solution:** Note that  $AB$  is an  $m \times p$  matrix.

Put  $V = \text{null}(AB) = \{x \in \mathcal{R}^p : ABx = 0\}$ , so  $\dim V = \dim \text{null}(AB)$ .

Put  $W = \{Bx : ABx = 0\} \subseteq \text{null}(A)$ .

Define the linear transformation  $T_B$  by:

$$T_B : V \rightarrow W : x \mapsto Bx.$$

Clearly the kernel of  $T_B$  is a subspace of  $\text{null}(B)$ , so  $\dim \ker(T_B) \leq \dim \text{null}(B)$ . (Probably you will notice that the kernel of  $T_B$  is exactly  $\text{null}(B)$ , but we don't need this.)

Also, since the image of  $T_B$  is contained in  $W$ , clearly  $\dim \text{Im}(T_B) \leq \dim(W) \leq \dim \text{null}(A)$ . Then since for any linear transformation  $T$ , the dimension of its domain equals the dimension of its kernel plus the dimension of its image, we have the following:

$$\dim \text{null}(AB) = \dim V = \dim \ker(T_B) + \dim \text{Im}(T_B) \leq \dim \text{null}(B) + \dim \text{null}(A).$$